AMENDMENT UNDER 37 C.F.R. § 1.111 Attorney Docket No.: Q86875

Application No.: 10/530,180

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions and listings of claims in the

application:

LISTING OF CLAIMS:

1. (currently amended): An in-wheel motor system for mounting a direct drive motor to a

steering wheel, comprising a first knuckle which is connected to the a non-rotary side of the

direct drive motor and locked in a steering direction does not turn and a second knuckle which is

connected to a steering rod and to the first knuckle in such a manner that it the second knuckle

ean-turns on a king pin axis in the steering direction and is fitted with a brake unit and the

steering wheel.

2. (currently amended): The in-wheel motor system for a steering-wheel according

to claim 1, wherein the non-rotary side of the motor is connected to the first knuckle by elastic

bodies and dampers, or elastic bodies having a spring or damper function.

3. (currently amended): The in-wheel motor system for a steering-wheel according

to claim 2, wherein the non-rotary side of the motor is supported by direct-moving guides and a

buffer member in the vertical direction of a vehicle.

4. (currently amended): The in-wheel motor system for a steering wheel according

to claim 3, wherein the non-rotary side of the motor is supported by direct-moving guides and a

buffer member in the horizontal direction of a vehicle in addition to the vertical direction.

5. (currently amended): The in-wheel motor system for a steering-wheel according

to any one of claims 2 to 4, wherein the output shaft of the motor and a wheel support hub

mounted to the second knuckle are interconnected by constant velocity joints.

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6. (currently amended): The in-wheel motor system for a steering-wheel according to any one of claims 2 to 4, wherein the rotary portion of the motor and the wheel are interconnected by a flexible coupling having at least two direct-moving guides connected to each other in such a manner that their moving directions cross each other in the axial direction of the motor and a constant velocity joint-like coupling which has the center of its movement on a king pin axis and turns in the steering direction.